

## TRIANGULATION ALGORITHM

Suppose we have a finite planar subdivision  $S$  on  $n$  vertices which consists of a large triangle  $Q$  and  $N$  polygons interior to  $Q$ . All of the finite regions may be triangulated in  $O(n \log n)$  time. At first, they may have little uniformity. The polygons themselves may have any number of reflex angles (angles whose measures exceed  $180^\circ$ ). In addition, one region consists of a triangle with  $N$  polygonal holes. By adding edges, however, we can break up as many of the  $N + 1$  regions as necessary and create a subdivision  $S'$  whose faces are all polygons monotone with respect to the  $x$ -axis. First, we describe a technique for triangulating monotone polygons. Secondly, we will discuss a method for decomposing the faces of a planar subdivision into polygons monotone with respect to the  $x$ -axis.

A polygon  $P$  with consecutive vertices  $v_1, v_2, \dots, v_m$ , leftmost vertex  $v_1$  and rightmost vertex  $v_j$  is monotone with respect to the  $x$ -axis iff both  $v_1, v_2, \dots, v_{j-1}, v_j$  and  $v_1, v_m, \dots, v_{j+1}, v_j$  are in increasing order of  $x$ -coordinate. We can merge these two sequences in time  $O(m)$  to form a sequence  $q_1, q_2, \dots, q_m$  containing all vertices of  $P$  in increasing order of  $x$ -coordinate. To triangulate  $P$ , we will move through these vertices in order, adding edges where possible and retaining on a stack those vertices already considered but which still lie on the boundary of a polygon yet to be triangulated.

Before describing the algorithm in general, let us consider the example in Figure <sup>1</sup>27. We begin by pushing  $q_1, q_2$  on the stack. Next, we consider  $q_3$ . It is already adjacent to  $q_2$  so an edge from  $q_3$  to  $q_2$  would be redundant. As the interior angle at  $q_2$  exceeds  $180^\circ$ , an edge from  $q_3$  to  $q_1$  could not lie inside the polygon. Push  $q_3$  on the stack. The next vertex,  $q_4$ , presents the same problems, so it too is pushed onto the stack. Vertex  $q_5$ , however, is adjacent to  $q_4$  and the interior angle at  $q_4$  measures less than  $180^\circ$ . We pop  $q_4$ , add edge  $e_1$ , and then consider the angle  $\angle q_5 q_3 q_2$ . As it also measures less than  $180^\circ$ , we pop  $q_3$ , add edge  $e_2$ , and then consider angle  $\angle q_5 q_2 q_1$ . As it is not smaller than a straight angle, an edge from  $q_5$  to  $q_1$  would not lie in the interior of  $P$ , so we push  $q_5$  and move to  $q_6$ . It is adjacent to  $q_1$ , the first vertex on the stack. We add the edges  $e_3$  and  $e_4$ , empty the stack, and then push  $q_5, q_6$ .  $q_7$  and  $q_6$  are adjacent and the current interior angle at  $q_6$  measures less than  $180^\circ$  so we can pop  $q_6$ , add  $e_5$ , and then push  $q_7$ . As the angle at  $q_7$  exceeds  $180^\circ$ , no edge can be added at  $q_8$ , so we push that vertex on the stack. The last vertex,  $q_9$  must be adjacent to both the bottom and top elements on the stack,  $q_5$  and  $q_8$ . We add  $e_6$ , the edge from  $q_9$  to the only middle element of the stack. Then we empty the stack, and stop.

The general algorithm proceeds as follows:

Begin

- 1)  $S[1] \leftarrow q_1$
  - 2)  $S[2] \leftarrow q_2$
  - 3)  $top \leftarrow 2$
  - 4) For  $i = 3$  to  $m$  begin
    - 5) If  $q_i$  is adjacent to  $S[top]$ , but not to  $S[1]$ , begin
      - 6) While  $top > 1$  and  $\angle_{q_i S[top] S[top-1]} < 180^\circ$  begin
        - 7) add an edge from  $q_i$  to  $S[top]$
        - 8)  $top \leftarrow top - 1$
      - end
      - 9)  $top \leftarrow top + 1$
      - 10)  $S[top] \leftarrow q_i$
    - end
    - 11) If  $q_i$  is adjacent to  $S[1]$ , but not to  $S[top]$ , begin
      - 12) For  $j = 2$  to  $top$ , add an edge from  $q_i$  to  $S[j]$
      - 13)  $S[1] \leftarrow S[top]$
      - 14)  $S[2] \leftarrow q_i$
      - 15)  $top \leftarrow 2$
    - end
    - 16) If  $q_i$  is adjacent to both  $S[1]$  and  $S[top]$ , begin
      - 17) For  $j = 2$  to  $top - 1$  add an edge from  $q_i$  to  $S[j]$
      - 18)  $top \leftarrow 0$
    - end
  - end
- End

Only when  $i = m$  and we are processing the last vertex is the condition of step 13 satisfied. Thus, only after processing the last vertex is the stack emptied (step 15). Each vertex is processed once prior to putting it on the stack. At most one edge is added as each vertex is popped from the stack. Thus the entire algorithm runs in linear time.

Now we wish to add edges between existing vertices in the planar subdivision  $S$  to achieve a planar subdivision  $S'$  whose faces are all polygons monotone with respect to the  $x$ -axis. First we must identify those vertices which violate the condition of monotonicity. Consider the example of Figure ~~A~~<sup>2</sup>. First we sort the vertices relative to their  $x$ -coordinate and label them  $v_1, \dots, v_{13}$ . At each vertex,  $v_i$ , we add two temporary vertical edges: one extends from  $v_i$  to the edge above, forming a temporary vertex there; the other extends from  $v_i$  to the edge below, also forming a

temporary vertex. When this process is complete, the faces of  $S'$  are all trapezoids whose bases are parallel to the  $y$ -axis (some are degenerate and form triangles with a single side parallel to the  $y$ -axis). [See Figure <sup>3</sup>B]. We focus on the 5 trapezoids which each contain a permanent vertex in the interior of a side. In each case, we add an edge from that vertex to another permanent vertex lying on the same trapezoid.

TRAPEZOID	EDGE
$T_1$	$(v_3, v_1)$
$T_2$	$(v_5, v_3)$
$T_3$	$(v_7, v_8)$
$T_4$	$(v_9, v_{10})$
$T_5$	$(v_{12}, v_{13})$

Following this procedure, delete all temporary edges. Six polygons monotonic in  $x$  result. [See Figure <sup>4</sup>C].

To add the temporary edges, we will sweep a vertical line across  $S'$  keeping an accurate list of active edges and their relationship to each other. Each edge will have a field which points to the edge above and a field which points to the edge below. The sweep line begins at  $v_1$  and  $v_2$ , the leftmost vertices. The edge  $e_1$  enters and leaves the data structure almost at the same instant. As the vertical line moves toward  $v_3$ , the data structure contains two edges. At  $v_3$ , two more edges are inserted into the data structure and the pointers are updated:

EDGE	ABOVE	BELOW
$e_2$	$e_4$	$\phi$
$e_3$	$\phi$	$e_5$
$e_4$	$e_5$	$e_2$
$e_5$	$e_3$	$e_4$

Since  $v_3$  joins  $e_4$  and  $e_5$ , we extend a vertical edge,  $t_1$ , from  $v_3$  to  $e_3$  and a second edge,  $t_2$ , from  $v_3$  to  $e_2$ . At  $v_4$ ,  $e_6$  replaces  $e_4$  in the data base and vertical edges are added from  $v_4$  to  $e_5$  and  $e_2$ . At  $v_5$ , two new edges are inserted, and at  $v_6$  another exchanges takes place. At  $v_7$ , two edges are deleted.

If we keep all of these edges in the leaves of a balanced tree and if each interior node contains the value of the uppermost edge of its subtree, then the processing time at each vertex is only  $O(\log n)$  where  $n$  is the number of vertices. Consequently, all of the temporary edges may be added to  $S'$  in time  $O(n \log n)$ . As  $S'$  is a planar graph, it contains fewer than  $2n$  trapezoids.

We can consider each one and add any necessary permanent edges in time  $O(n)$ . Thus the overall time of this algorithm is  $O(n \log n)$ .

#### BIBLIOGRAPHIC NOTES

The algorithm for triangulating monotone polygons is due to Garey, Johnson, Preparata and Tarjan [GJPT78]. The method of decomposition of a the faces of a planar subdivision into monotone polygons is derived from the work of Chazelle and Incerpi [Ch84b] and [CI83].

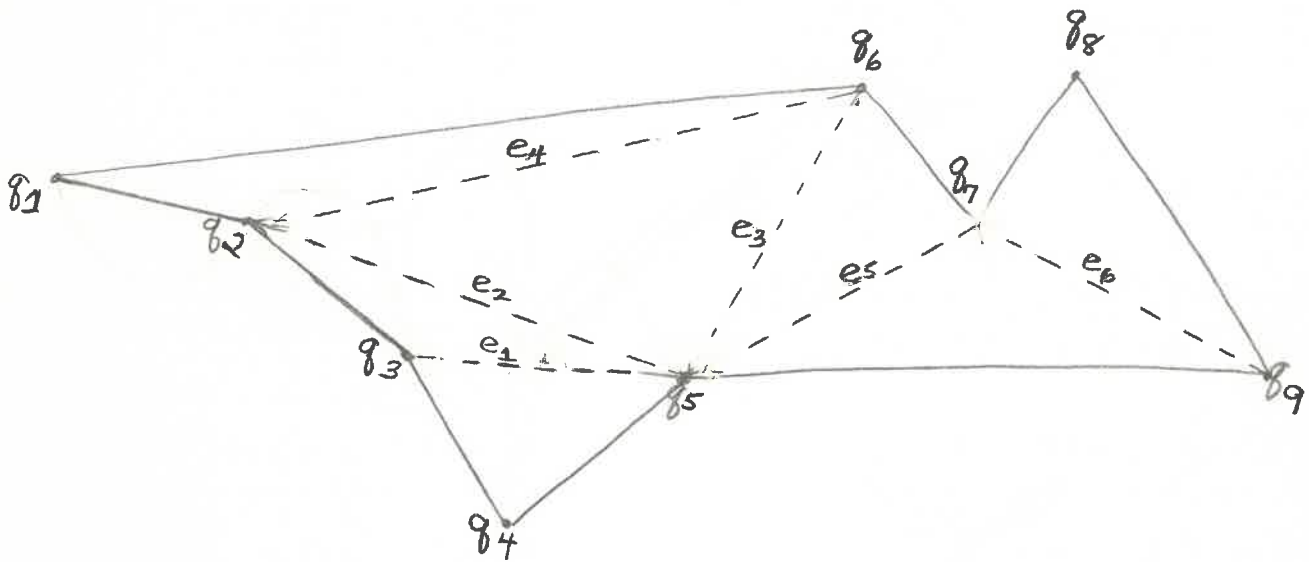


FIGURE 1

TRIANGULATION OF A MONOTONE POLYGON

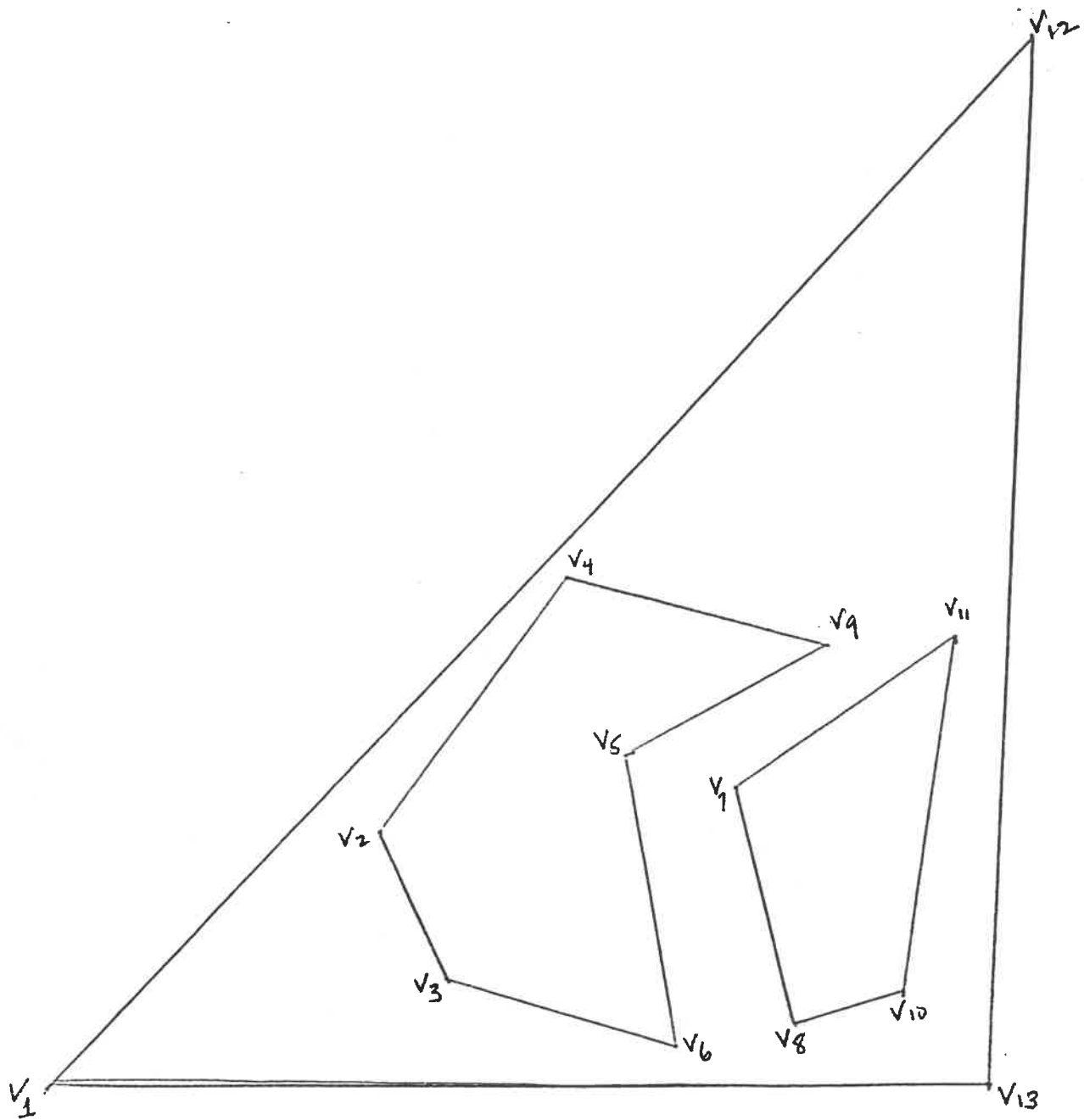


FIGURE 2