

HALT_{TM}

Prove that

$\text{HALT}_{\text{TM}} = \{\langle M, w \rangle \mid M \text{ is a TM and } M \text{ halts on input } w\}$

is undecidable.

Proof by reduction: A_{TM} to HALT_{TM}

Initial Assumption: There exists a TM, $D_{\text{HALT}}\langle M \rangle$, that can decide HALT_{TM} .

We will now build a decider for A_{TM} that takes input $\langle M, w \rangle$ and uses D_{HALT} to determine if M accepts w . This decider, D_A , will function as follows:

- 1.) Run D_{HALT} on input $\langle M, w \rangle$
- 2.) If D_{HALT} rejects, REJECT
- 3.) If D_{HALT} accepts, then simulate M on input w
 - If M accepts w , ACCEPT
 - If M rejects w , REJECT

Case 1: $\langle M, w \rangle \in A_{\text{TM}}$ In this case M accepts w and thus halts, so D_{HALT} will accept $\langle M, w \rangle$ and D_A will accept during the simulation of M on w .

Case 2: $\langle M, w \rangle \notin A_{\text{TM}}$ This means that M either rejects or loops on input w . If M loops on w then D_{HALT} will reject $\langle M, w \rangle$ causing D_A to reject. If M rejects w then D_{HALT} will accept $\langle M, w \rangle$ and D_A will reject during the simulation of M on w .

Given our initial assumption that HALT_{TM} was decidable, we were able to construct a decider for A_{TM} . However, we know that A_{TM} is undecidable. Thus we can conclude that our initial assumption was false and that HALT_{TM} is undecidable. ■