

Class #19:  
Convolutional Neural Networks

Machine Learning (COMP 135): M. Allen, 06 Nov. 19

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## Neural Networks for Images

- ▶ A regular feed forward network can sometimes prove problematic for image-processing tasks
  - ▶ Given a  $(100 \times 100)$  pixel color image, each with 3 color-channel (e.g. RGB) values, we end up with many, many weights to be learned
  - ▶ In addition, a 1-D weight-vector doesn't carry any real information about **spatial relationships** between image features (edges, blocks of color, ...)

30,000 weights/neuron

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## Convolutional Neural Networks (CNNs)

- ▶ To capture image dynamics, and expand what the networks can do, we organize neurons into stacks of 3-dimensional volumes
  - ▶ Each is connected to later volumes, filtering and flattening down to the usual final  $(C \times 1)$  classification-output layer (where  $C$  is the number of classes)

$(100 \times 100 \times 3)$   
input layer

$(W_1 \times H_1 \times D_1)$   
hidden layer

$(W_2 \times H_2 \times D_2)$   
hidden layer

$(C \times 1)$   
output layer

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## Types of Layers in CNNs

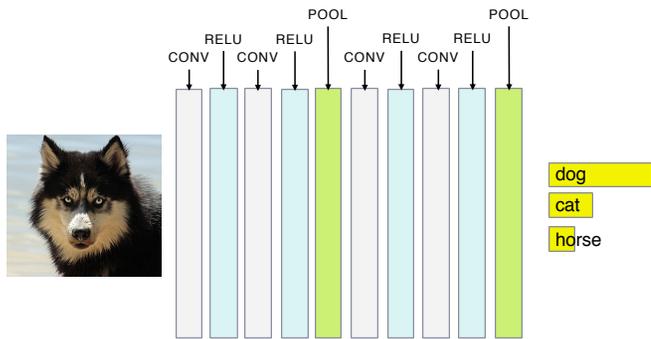
- ▶ **INPUT:** as in a typical NN, each neuron corresponds to a single **input feature-value**
  - ▶ Only the 3-D arrangement is different
- ▶ **OUTPUT:** again, as in a typical NN, these are **fully-connected layers**
  - ▶ Each neuron is connected to all of those in the volume above
  - ▶ Each computes a function, like the sigmoid (*softmax*), typically giving probabilities for each of the possible output classes
- ▶ **OTHER:** layers between can play different possible roles
  1. **CONVOLUTION:** transformations on **sub-regions**
  2. **RELU:** application of the  $\max(0, x)$  function
  3. **POOLING:** **down-sampling** to reduce volume size

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## Deep Convolutional Networks

- ▶ For complex image-classification tasks, we may use many layers, combining the types over and over again



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## Convolutional (CONV) Layers

- ▶ The core innovation in a CNN is the idea of a **spatial filter**, which is a 3-D volume where:

1. Each neuron in one layer computes a function on a proper **sub-region** of the layer above
2. We form the CONV layer by “tiling” the prior layer, in (possibly) overlapping sub-regions
3. Every neuron in one layer shares a **single set** of weights, and so computes the same function

- ▶ Two main decisions in building such a layer:

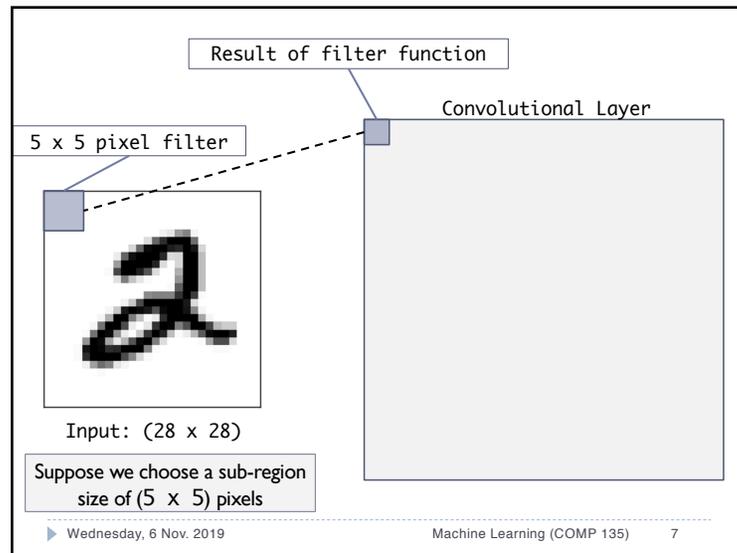
1. What **size** of sub-region should we use?
2. What is our **stride**; i.e., **how far** do we move over each time we connect our next sub-region?

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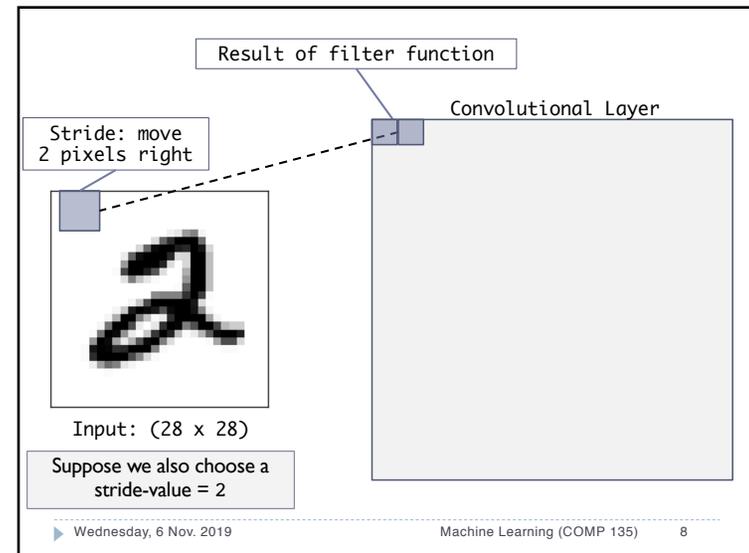


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### Convolutional Layer: (14 x 14)

"Off-edge" pixel values all set to 0

Input: (28 x 28)

Since stride = 2, the result is a layer with half as many neurons

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### A Full Convolutional Layer

The 3-dimensional CONV layer consists of a stack of  $N$  such filters, of dimensionality: (14 x 14 x  $N$ )

Every neuron in each filter-layer *shares* a single set of common weights, applied to inputs, with the products summed as usual.

$N$  different convolutions

(28 x 28)

(14 x 14)

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### ReLU (Activation) Layers

- CONV layer may or may not change input size (depends upon stride)
- ReLU layer keeps size the same, simply applying its function to neurons
- ReLU is very popular, but other activation function layers are allowed

Filter value:  $x$

Convolutional Layer (14 x 14)

Activation value:  $\text{ReLU}(x)$

ReLU Layer (14 x 14)

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### Combining Layers

Using a 3-dimensional convolutional layer of multiple filters means that we will have a matching number of activation layers.

$N$  different convolutions  $N$  different activations

(28 x 28)

(14 x 14)

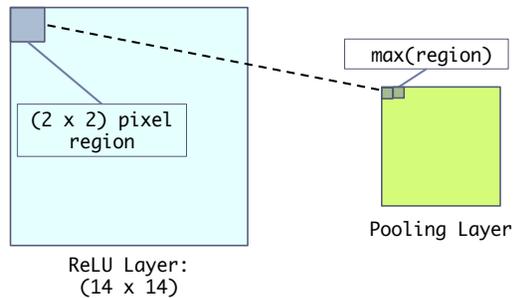
(14 x 14)

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## Pooling Layers

- ▶ While CONV and ReLU layers can compute more complex functions, POOL layers **down-sample** a region, reducing it to something simpler (usually its MAX value)



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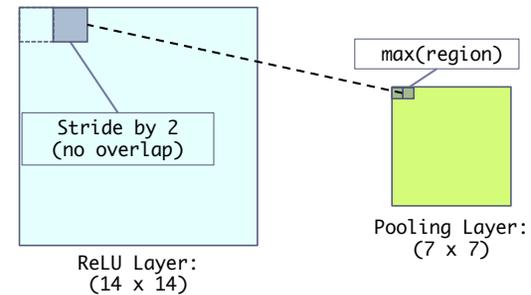
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## Pooling Layers

- ▶ Again, we stride across the layer, reducing the overall size by avoiding overlap
- ▶ Most common approach:  $(2 \times 2)$  region, with stride = 2



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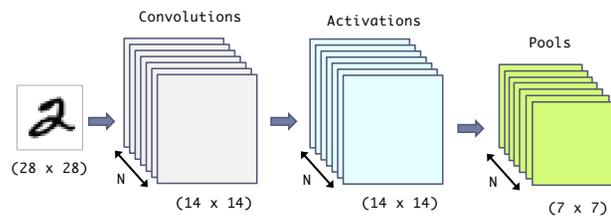
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## Combining Layers

Again, each layer is 3-dimensional (until the final output layer).



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## Uses of CNNs and Other Deep Networks

- ▶ Convolutional networks have become increasingly popular for image and other spatial data
- ▶ Browser-based demos:
  - <https://cs.stanford.edu/people/karpathy/convnetjs/>
- ▶ A variety of applications of neural network models to a number of research problems

<https://youtu.be/Bui3DWs02h4>

<https://youtu.be/hPKJBXkyTKM>

<https://youtu.be/aKSILzbAqJs>

- ▶ Cat drawings!

<https://affinlayer.com/pixsrv/>

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## Next Few Weeks

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- ▶ **Topics:** Boosting Classifiers, Reinforcement Learning
- ▶ **No class:** Monday, 11 November (Veteran's Day)
- ▶ **HW 05:** due Wednesday, 20 November, 9:00 AM
  - ▶ Posted by tomorrow, end of day
- ▶ **Project 02:** due Monday, 25 November, 9:00 AM
- ▶ **Office Hours:** 237 Halligan, Tuesday, 11:00 AM – 1:00 PM
  - ▶ TA hours can be found on class website as well

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