

## Bayesian Linear Regression

data: observe pairs  $\{x_i, y_i\}_{i=1}^N$

goal: given new  $x_*$ , predict its  $y_*$  or sample plausible  $y_*$   
across many possible  $x$ , what is shape of  $y(x)$ ?

model:

$$y_i = y(x_i) = f(x_i) + \varepsilon_i$$

deterministic "noise"

$\varepsilon_i \sim N(0, \sigma_n^2)$   
 $n$  for noise

Assume a linear model for mean function

$$f(x_i) = w * x_i \quad \text{in 1D}$$

$$= w^T x_i \quad \text{when } x_i \text{ is a D-dim vector}$$

Picture



several possible values for slope  $w$   
are likely/plausible

Assume Gaussian prior on weights  $w$

$$w \sim N(0, \sigma_p^2) \quad \text{in 1D}$$

$$p(w) = \vec{w} \sim N(0, \Sigma_p) \quad \text{in D-dimensions}$$

Goal:

what is  $p(w|x, y)$ ?

Bayes thm says:

$$p(w|x, y) = \frac{p(y|x, w) p(w)}{p(y|x)} = \frac{\text{lik} * \text{prior}}{\text{marg. lik.}}$$

## 1D posterior computation

$$\begin{aligned}
 p(w|y, x) &\propto \frac{\text{const}}{p(y|x)} p(w) \prod_{i=1}^N p(y_i|x_i, w) \\
 &\propto N(\mu, \tau_p^2) \prod_{i=1}^N N(y_i|w \cdot x_i, \tau_n^2) \\
 &\propto \exp\left\{-\frac{1}{2} \frac{1}{\tau_p^2} w^2\right\} \prod_{i=1}^N \exp\left\{-\frac{1}{2} \frac{1}{\tau_n^2} (y_i - w \cdot x_i)^2\right\} \\
 &\propto \exp\left\{-\frac{1}{2} \left( \frac{1}{\tau_p^2} w^2 + \frac{1}{\tau_n^2} \sum_{i=1}^N (y_i - w \cdot x_i)^2 \right)\right\} \\
 &\propto \left( \frac{1}{\tau_p^2} w^2 + \frac{1}{\tau_n^2} \left[ \sum_i y_i^2 - 2 \sum_i y_i w x_i + w^2 \sum_i x_i^2 \right] \right) \\
 &\quad \textcircled{a} \\
 &\propto \exp\left\{-\frac{1}{2} \left( \frac{1}{\tau_p^2} + \frac{1}{\tau_n^2} \sum_i x_i^2 \right) w^2\right\} \\
 &\quad \textcircled{b} \\
 &\propto \exp\left\{-\frac{1}{2} a w^2 - b w\right\} \\
 &\quad \text{"complete the square"} \\
 &\quad \text{add } -\frac{1}{2} ab^2 \\
 &\quad \text{which is const wrt } w \\
 &\propto \exp\left\{-\frac{1}{2} a \left(w - \frac{b}{a}\right)^2\right\} \\
 \text{looks like Gaussian pdf!} &\propto \exp\left\{-\frac{1}{2} \frac{1}{\sigma^2} (w - \mu)^2\right\} \\
 \sigma^2 = \frac{1}{a} &= \left( \frac{1}{\tau_p^2} + \frac{1}{\tau_n^2} \sum_i x_i^2 \right)^{-1} \quad \mu = \frac{b}{a} = \frac{\frac{1}{\tau_n^2} (\sum_i y_i x_i)}{\frac{1}{\tau_p^2} + \frac{1}{\tau_n^2} \sum_i x_i^2}
 \end{aligned}$$

Key Idea: Gaussian prior + Gaussian likelihood  $\rightarrow$  Gauss posterior

Assuming model is good, we now can do closed form predictions  
Compute exact samples for this posterior

General multivariate posterior with  $D \geq 1$  dims

$$p(\omega) = N_D(\omega | 0, \Sigma_p)$$

$$p(y_i | x_i, \omega) = N_1(y_i | \omega^T x_i, \tau_n^{-2}) \quad (y_i \text{ still scalar})$$

We apply same process

$$\begin{aligned} p(\omega | y, x) &\propto \frac{1}{p(y|x)} p(\omega) \prod_{i=1}^N p(y_i | x_i, \omega) \\ &\propto N(\omega | 0, \Sigma_p) \prod_i N(y_i | \omega^T x_i, \tau_n^{-2}) \\ &\propto \exp\left\{-\frac{1}{2} \omega^T \Sigma_p^{-1} \omega\right\} \exp\left\{-\frac{1}{2} \sum_{i=1}^N (\vec{y}_i - \vec{x}_i^T \vec{\omega})^T (\vec{y}_i - \vec{x}_i^T \vec{\omega})\right\} \\ &\quad X: D \times N \text{ matrix} \\ &\quad \begin{bmatrix} x_1^T & \cdots & x_k^T & \cdots & x_N^T \end{bmatrix} \\ &\propto \exp\left\{-\frac{1}{2} (\omega - \mu)^T \Sigma^{-1} (\omega - \mu)\right\} \end{aligned}$$

~~Posterior~~ Posterior:  $p(\omega | y, x) = N(\omega | \mu, \Sigma)$

~~$A = \Sigma^{-1} = \Sigma_p^{-1} + \frac{1}{\tau_n^2} X X^T$~~

Concept check

Does it match 1D case?  
Do dims work?

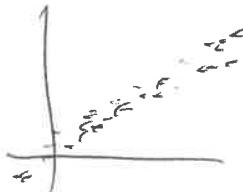
What is posterior if no data observed?

$$\mu = \frac{1}{\tau_n^2} A^{-1} X \vec{y}$$

Beyond Linear Features

## Kernel Trick

In previous ML course, should have seen more flexible features



linear OK



linear will FAIL

Possible feature maps:

$$\phi(x) = \begin{bmatrix} 1 \\ x \\ x^2 \end{bmatrix} \text{ "quadratic" or } \begin{bmatrix} 1 \\ x \\ \cos(x) \\ \sin(x) \end{bmatrix} \text{ "periodic"}$$

New regression model

$$y(x_i) = w^T \phi(x_i) + \epsilon_i$$

linear in  
FEATURE  
space

noise

$$\phi(x_i) = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} \text{ Fdim  
feature  
space}$$

Now, can write posterior as

w also has  
length F

$$p(w|y, x) = N(w | \frac{1}{\tau_n^2} A^{-1} \Phi \tilde{y}, A^{-1})$$

$$\text{where } A = \Sigma_p^{-1} + \frac{1}{\tau_n^2} \Phi \Phi^T$$

Can write posterior predictive as

check how big is A?

$$p(f_* | x_*, x, y) = N(f_* | \frac{1}{\tau_n^2} \phi(x_*)^T A^{-1} \Phi \tilde{y}, \phi(x_*)^T A^{-1} \phi(x_*) )$$

What values will function take  
at new test points?

Consider a neat way to rewrite

$A$  has size  $F \times F$

$$\text{posterior} = \phi(x_*)^T A^{-1} \phi(x_*)$$

$$= \phi(x_*)^T \left( \sum_p^{-1} + \frac{1}{\tau_n^2} \Phi \Phi^T \right)^{-1} \phi(x_*)$$

$$K = \Phi^T \sum_p \Phi$$

is  $N \times N$

$$= \phi(x_*)^T \sum_p \phi(x_*) - \phi(x_*)^T \sum_p \Phi (K + \tau_n^2 I)^{-1} \Phi^T \sum_p \phi(x_*)$$

Using MATRIX INVERSION LEMMA

When  $N < F$ , cheaper to solve using "K" formula  
 this is the kernel trick, never need to fully represent feature vectors

define function

$$k(x, x') = \phi(x)^T \sum_p \phi(x')$$

We'll call this a kernel function

output: scalar, aka covariance function

larger values  $\Rightarrow$   $x$  and  $x'$  are closely correlated  
 zero  $\Rightarrow$   $x, x'$  not related

$$\text{posterior}^2 = k(x_*, x_*) - k(x_*, x) \left[ k(x, x) + \tau_n^2 I_N \right]^{-1} k(x, x_*)$$

$$\mu_{\text{posterior}} = k(x_*, x) \left[ k(x, x) + \tau_n^2 I_N \right]^{-1} y$$

$1 \times N \quad N \times N \quad N \times N \quad N \times 1$

## For Next Time: Gaussian Process

Read R & W Ch. 2, esp. 2.2 which will be in-class focus  
 submit critical comments to Canvas!

GPs let us take advantage of kernel trick  
 to use very flexible feature embeddings  $\phi(x)$   
 that might be infinite in dimension

GPs use the Gaussian and its useful properties

- conjugacy
- marginalization

$$\text{if } p(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}) = N\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mid \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right) \\ \text{then } p(x_1) = N(x_1 \mid \mu_1, \Sigma_{11})$$

Seen: Weights view

prior is on vector  $w$

$$w \sim p(w)$$

$$y|x \sim p(y \mid w^T \phi(x), \sigma_n^2)$$

New: Function view

prior is over possible function values

$$\text{specify } m(x) = \mathbb{E}[f(x)]$$

$$k(x, x') = \text{Cov}[f(x), f(x')]$$

$$\begin{array}{c|c} f_1 & x_1 \\ f_2 & x_2 \\ \vdots & \vdots \\ f_N & x_N \end{array} \sim GP()$$

$$\sim N(\underline{\text{mean}}, \underline{\text{covar}})$$