Recovery of jump table case statements from binary code

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Abstract

One of the fundamental problems with the static analysis of binary (executable) code is that of recognizing, in a machine-independent way, the target addresses of n-conditional branches implemented via a jump table. Without these addresses, the decoding of the machine instructions for a given procedure is incomplete, leading to imprecise analysis of the code.

In this paper we present a technique for recovering jump tables and their target addresses in a machine and compiler independent way. The technique is based on slicing and copy propagation. The assembly code of a procedure that contains an indexed jump is transformed into a normal form which allows us to determine where the jump table is located and what information it contains (e.g. offsets from the table or absolute addresses).

The presented technique has been implemented and tested on SPARC and Pentium code generated by C, C++, Fortran and Pascal compilers. Our tests show that up to 89% more of the code in a text segment can be found by using this technique, when compared against the standard method of decoding. The technique was developed as part of our retargetable binary translation framework UQBT; however, it is also suitable for other binary-manipulation and analysis tools such as binary profilers, instrumentors and decompilers. © 2001 Published by Elsevier Science B.V.

Keywords: Binary translation; Binary analysis; Slicing; Jump tables

1. Introduction

The ever-growing reliance on software and the continued development of newer and faster machines has increased the need for machine-code tools that aid in the migration, emulation, debugging, tracing, and profiling of legacy code. Amongst these tools are: binary translators [19,20], emulators/simulators [8,23], code instrumentors [1,17,21], disassemblers [9,15], and decompilers [5,12].

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The fundamental problem in decoding machine instructions is that of distinguishing code from data—both are represented in the same way in von Neumann machines. Given an executable program, the entry point to that program is given in the program’s header. Information on text and data sections is also given in the header. However, data can also be stored in text areas, without such information being stored in the executable program’s header. Therefore, there is a need to analyze the code that is decoded from the text area(s) of the program, and separate data from code.

The standard method of decoding machine code involves following all reachable paths from the entry point [5,19]. This method does not give a complete coverage of the text space in the presence of indirect transfers of control such as indexed jumps and indirect calls. A common technique used to overcome this problem is the use of patterns. A pattern is generated for a particular compiler to cater for the way in which the compiler, or family of compilers, generate code for an indexed jump. This technique is extensively used as most tools deal with a particular set of compilers; for example, TracePoint only processes Windows binaries generated by the Microsoft C++ compiler [21]. In the presence of optimized code, patterns do not tend to work very effectively, even when the code is generated by a compiler known to the pattern recognizer.

In this paper we present a technique to recover the targets of indexed jumps on a variety of machines and languages. This technique is based on slicing of binary code and copy propagation into a normal form. Section 2 summarizes techniques described in the literature for the compilation of $n$-conditional branch statements into assembly code. Section 3 presents several Pentium and SPARC examples of code that use jump tables, Section 4 explains our normalization technique, Section 5 provides results on the use of this technique in existing benchmarks programs, and Section 6 gives previous work in this area. The paper contains an appendix with additional interesting examples.

2. Compiler code generation for $n$-conditional branches

$n$-conditional branches were first suggested by Wirth and Hoare in 1966 [24,25] as a useful extension to the Algol language. An $n$-conditional branch allows a programming language to determine one of $n$ branches in the code. This extension was implemented in Algol 68 in a form that allowed its use as a statement or an expression. In other words, the result of the case statement could be assigned to a variable. This high-level statement has evolved to the well known switch statement in C and the case statement in Pascal, where labels are used for the different arms of the conditional branch, and a default arm is allowed, as per Fig. 1. The C code shows the indexed variable num which is tested against the values in the range 2–7 for individual actions, and if not successful, defaults to the last default action.

Although not commonly documented in compiler textbooks, compiler writers generate different types of machine code for $n$-conditional branches. These ways of
generating $n$-conditional branches are determined by talking to compiler writers or reverse engineering executable code. Several techniques for generating $n$-conditional branches from a compiler were documented in the 1970s and 1980s, when optimization for space and speed was an important issue. The most common techniques are described here based on [18].

The simplest way of generating code for an $n$-conditional branch is as a linear sequence of comparisons against each arm in the statement. This form is efficient for a small number of arms, typically 4 or less. A more sophisticated technique is the if-tree, where the selection is accomplished by a nested set of comparisons organized into a tree. The most common implementation is a jump table, which may hold labels or offsets from a particular label. This implementation requires a range test to determine the membership of values on the table. Although jump tables are the fastest method when there are many arms in the $n$-conditional branch, jump tables are space-wise inefficient if the case values are sparse. In such situation, a search tree is the most convenient implementation. When the arms of the $n$-conditional branch are sparse but yet can be clustered in ranges, a common technique used is to combine search trees and jump tables to implement each cluster of values [10,13]. This paper deals with the issue of recovering code from generated jump tables, in such a way that the target addresses of an indexed jump are determined. This paper does not attempt to recover high-level $n$-conditional branch statements, but rather the information necessary to translate an indirect branch indexing a jump table.

For an $n$-conditional branch implemented using a jump table, an indexed table is set up with addresses or offsets for each of the cases of the branch. The table itself is located in a read-only data section, or mixed in with the text section. In the interest of efficiency, range tests for such jump tables need to be concise. The most common

```c
#include <stdio.h>

int main()
{
    int num;
    printf("Input a number, please: ");
    scanf("%d", &num);
    switch(num) {
      case 2:
        printf("Two!\n"); break;
      case 3:
        printf("Three!\n"); break;
      ...  
      case 7:
        printf("Seven!\n"); break;
      default:
        printf("Other!\n"); break;
    }
    return 0;
}
```

Fig. 1. Sample switch program written in the C language.
way of doing both tests is as follows [2]:

1  
k <- case_selector - lower_bound
2  
3  compare k with (upper_bound - lower_bound)
4    if unsigned_greater goto out_of_range
5  
6  assertion: lower_bound <= case_selector <= upper_bound

If the case selector value is within the bounds of the upper and lower bounds, an offset into the jump table is calculated based on the size of each entry in the table; typically 4 bytes for a 32-bit machine. Based on the addressing modes available to a machine, either an indirect jump on the address of the table plus the offset, or an indexed jump on the same values is generated. The machine then continues execution at the target of the indirect/indexed jump.

Retargetable compilers also use these techniques. A brief description for the code generation of an indirect jump through a jump table for a retargetable C compiler is given in [11] by the following specification:

15  
if t1 < v[l] goto lolab ; l=lower bound
16  if t1 > v[u] goto hilab ; u=upper bound
17  goto *table[t1-v[l]]

Overall, compiler writers use a variety of heuristics to determine which code to generate for a given \( n \)-conditional branch based on the addressing modes and instructions available on the target machine. It is also common for a compiler to have more than one way of emitting code for such a construct, based on the number of arms in the conditional branch and the sparseness of the values in such arms.

3. Examples of existing indexed jumps in binary code

This section presents examples of Pentium and SPARC code that make use of jump tables. The examples aim to familiarize the reader with a variety of ways of encoding an \( n \)-conditional branch in assembly code, as well as to show the degree of complexity of such code. The assembly code for the examples was generated by the Unix utility dis. This disassembler uses the convention of placing the destination operand on the right of the instruction. The examples show annotated native Pentium and SPARC assembly code, and where relevant, the address for the assembly instructions or the indexed table. The annotations were included in these examples for ease of readability; they are not part of the produced disassembly.

The first two examples in Figs. 2 and 3 were generated by the cc compiler on a Solaris Pentium and SPARC machine respectively, from the sample program in Fig. 1.

In Fig. 2, register eax is used as the index variable; its value is read from a local variable on the stack ([ebp-8], the case selector). The lower bound and the range of the table are checked (2 and 5, respectively); the code exits if the value of the index variable is out of bounds. If within bounds, an indexed scaled jump on (eax*4) is
performed, offset from the start of the indexed table at 0x8048a0c. The contents of the values of the table are of addresses; each is displayed in little-endian format.

Fig. 3 performs the same logical steps as Fig. 2 using SPARC assembly code, where indexed jumps do not exist but indirect jumps on registers are allowed. In the example, the indexed variable is initially in o0, which gets set from a local variable on the stack ([fp-20], the case selector). The lower bound is computed and the indexed variable is set to o1. The range of the table is checked; if out of bounds, the code exits to address 0x10980. If within bounds, the address of the table is computed to o0 (by the sethi and or instructions), the indexed register is multiplied by 4 to get the right 4-byte offset into the indexed table, and the value of the table (o0) indexed at o1 is fetched into o0. A jump to o0 is then performed.

Fig. 4 presents a SPARC example that uses a hash function to determine how to index into the table. The code comes from the Solaris 2.5 vi program. The index variable is set as o0, and it is normalized by subtracting its lower bound. The range of the table is checked; if the value is out of range, a jump to the end of the case statement...
is performed (0x18804). If within bounds, the table’s address is set in register o2. The indexed register is hashed into o1 and multiplied by 8 (into o4) to get the right offset into the table (as the table contains two 4-byte entries per case). A word is loaded from the table into register o3 and its value is compared against the hash function key (the normalized index variable o0). If the value matches, the code jumps to address 0x1885c, where a second word is read from the table into o0, and a register jump is performed to that address. In the case where the value fetched from the table does not match the key, an end-of-hashing comparison is performed against the value -1. If -1
Our last example, Fig. 5, is from the m88ksim SPEC95 benchmark suite. This example shows 3 groups of tests on bits of a field within a structure, which get stored in registers edx, ecx and eax. The three partial results are then or’d together to get the resultant indexed variable in register ecx. The upper bound is checked (7) and, if within bounds, a branch to address 0x8058045 is taken, where an indexed branch is made on the contents of register ecx, scaled by the right amount (4), and the table address. Note that the branch (jbe) is the opposite of that normally found in switch statements (i.e. ja). This illustrates the danger of relying on patterns of instruction to recover indexed branch targets; such a piece of code could not be well specified in a pattern. For the interested reader, this code was produced from the C macro in Fig. 6. The appendix illustrates more examples.

4. Our technique

We have developed a technique to recover jump table branches from disassembled code. The technique is architecture, compiler and language independent, and has
been tested on CISC and RISC machines with a variety of languages and compilers (or unknown compiler, when dealing with precompiled executables). Development of general techniques is an aim in our work as analysis of executable code should not rely on particular compiler knowledge; this knowledge prevents the techniques from working with code generated by other compilers, and in most cases, for other machines.

There are 3 steps to our technique:

1. Slice the code at the indexed/indirect register jump.
2. Perform copy propagation to recover pseudo high-level statements.
3. Check against indexed branch normal forms to determine the type of jump table.

4.1. Slicing of binary code

Our executable code analysis framework allows for the disassembly of the code into an intermediate representation composed of register transfer lists (RTL) [6] and control flow graphs for each decoded procedure in the program. The RTL describes the effects of machine instructions in terms of register transfers, and is general enough to support RISC and CISC machine descriptions.

When an indexed or indirect jump is decoded, we create an intraprocedural backward slice of the disassembled binary code [4]. Slicing occurs by following the transitive closure of registers and condition codes that are used in a given expression. The stop criterion for a given register along a path is when that register is loaded from memory (i.e. from a local variable, a procedure argument, or a global variable), it is returned by another function, or it reaches the start of the procedure without being defined (and hence it is a register parameter set by the caller).

For the purposes of determining jump tables, we have an extra stop criterion: if the lower bound of the indexed jump is found, and other relevant information has been found, no more slicing is performed. Of course, this condition is not always satisfied as indexed tables whose first entry corresponds to the register being zero do not need to check for the lower bound. In such cases, the slice finishes by means of the other stop conditions. In the case of slices across calls, we stop if the register is returned by the call (i.e. eax on Pentium or o0 on SPARC); in other cases we assume registers are preserved across calls and continue slicing. This is a heuristic that works well in
practice and is used rarely. The heuristic works when the machine code conforms to
the operating system’s application binary interface [22].

For example, for Fig. 2, the following slice is created using RTL notation:

1. \( \text{eax} = m[\text{ebp}-8] \)
2. \( \text{eax} = \text{eax} - 2 \)
3. \( ZF = (\text{eax} - 5) = 0 ? 1 : 0 \)
4. \( CF = (\neg \text{eax}@31 \& 5@31) | ((\text{eax}-5)@31 \& (\neg \text{eax}@31 \| 5@31)) \)
5. \( PC = (\neg CF \& \neg ZF) = 1 ? \text{<exit>} : \text{<step 6>} \)
6. \( PC = m[0x8048a0c + \text{eax} \* 4] \)

Register ebp points to the stack, therefore indexed variable eax fetches a value from
the local memory for that procedure. The indexed register is normalized by subtracting
the lower bound (2) and its range is checked against 5 (the difference between
the upper and lower bounds). If within bounds, an indexed jump is performed at
statement 6.

4.2. Copy propagation

Once a slice has been computed, we perform copy propagation on registers and con-
dition codes. This is a common technique used in reverse engineering when recovering
higher-level statements from more elementary ones, such as assembly code [3,7] and
COBOL code [14].

As per [7], a definition of a register \( r \) at instruction \( i \) in terms of a set of \( a_k \) registers,
\( r = f_1(\{a_k\}, i) \), can be copy propagated at the use of that register on another instruction
\( j \). \( s = f_2(\{r, \ldots \}, j) \), if the definition at \( i \) is the unique definition of \( r \) that reaches \( j \)
along all paths in the program, and no register \( a_k \) has been redefined along that path.
The resulting instruction at \( j \) would then look as follows:

\[
s = f_2(f_1(\{a_k\}, i), \ldots, j)
\]

and the need for the instruction at \( i \) would disappear. The previous relationship is partly
captured by the definition-use (du) and use-definition (ud) chains of an instruction: a
use of a register is uniquely defined if it is only reached by one instruction, that is,
its ud chain set has only one element. This relationship is known as the \( r \)-clear\(_{i\rightarrow j} \)
relationship for register \( r \). More formally,

\[
s = f_2(f_1(\{a_k\}, \ldots, j), \text{iff } |\text{ud}(r, j)| = 1 \land
ud(r, j) = i \land
j \in \text{du}(r, i) \land
\forall a_k \bullet a_k \text{-clear}_{i \rightarrow j}
\]

Note that this definition does not place a restriction on the number of uses of the
definition of \( r \) at \( i \). Hence, if the number of elements on \( \text{du}(r, i) \) is \( n \), instruction \( i \)
can potentially be substituted into \( n \) different instructions \( j_k \), provided they satisfy the \( r\)-clear\(_{i\rightarrow j_k} \) property.

In our example of Fig. 2, the application of copy propagation to the slice found in Section 4.1 gives the following pseudo-high-level statements:

\[
\begin{align*}
(3) & \quad \text{jcond} ([ebp-8] > 7) \text{ <exit>} \\
(4) & \quad \text{jmp} [0x8048a0c + ([ebp-8] - 2) \times 4]
\end{align*}
\]

where \( \text{jcond} \) stands for conditional jump and \( \text{jmp} \) stands for unconditional jump. Statement 3 checks if the case selector is outside the bounds of the jump, and statement 4 performs a jump to the content (i.e. an address) of memory location \( 0x8048a0c + ([ebp-8] - 2) \times 4 \).

4.3. Normal form comparison

Our previous example can be rewritten in the following way:

\[
\begin{align*}
\text{jcond} (\text{var} > \text{num}_u) \text{ X} \\
\text{jmp} [T + (\text{var} - \text{num}_l) \times w]
\end{align*}
\]

where \( \text{var} \) is a local variable, for example \([ebp-8]\), \( \text{num}_u \) is the upper bound for the \( n \)-conditional branch, for Example 7, \( \text{num}_l \) is the lower bound of the \( n \)-conditional branch, for example 2, \( T \) is the indexed table’s address (and is of type address), for example \( 0x8048a0c \), and \( w \) is a constant equivalent to the size of the word of the machine; 4 in this example. Based on this information, we can infer that the number of elements in the indexed table is \( \text{num}_u - \text{num}_l + 1 \), for a total of 6 in the example. The example also shows that the elements of the indexed table are labels (i.e. addresses) as the jump is to the target address loaded from the address at \( 0x8048a0c + ([ebp-8] - 2) \times 4 \).

The previous example only shows one of several normal forms that are used to encode \( n \)-conditional branches using a jump table. We call the previous normal form type A. Fig. 7 shows the 3 different normal forms that we have identified in executable code that runs on SPARC and Pentium. Normal form A (address) is for indexed tables that contain labels as their values. Normal form O (offset) is for indexed tables that contain offsets from the start of the table \( T \) to the code of each case. Normal form H (hashing) contains labels or offsets in the indexed table. Form O can also be found in a position independent version as well. Normal form H contains pairs (\( \langle \text{value} \rangle, \langle \text{address} \rangle \)) at each entry into the jump table.

In our 4 examples of Figs. 2–5, we find the following normal forms, respectively:

\[
\begin{align*}
\text{• jcond} (r[24] > 5) & \quad 0x80489dc \\
\text{jmp} [0x8048a0c + (r[24] \times 4)] & \Rightarrow \text{normal form A}
\end{align*}
\]
Fig. 7. Normal forms for \( n \)-conditional code after analysis.

<table>
<thead>
<tr>
<th>Type</th>
<th>Normal Form</th>
<th>Types of &lt;expr&gt; allowed</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>( \text{jcond } (r[9] &gt; \text{num}_a) \times \text{X} )\n( \text{jmp } [T + &lt;\text{expr} &gt; \times w] )</td>
<td>( r[v] )\n( r[v] - \text{num}_t )\n( (r[v] - \text{num}_t) &lt;&lt; 24 ) &gt;&gt; 24</td>
</tr>
<tr>
<td>O</td>
<td>( \text{jcond } (r[v] &gt; \text{num}_a) \times \text{X} )\n( \text{jmp } [T + &lt;\text{expr} &gt; \times w] + T \text{ or} )\n( \text{jmp } \text{PC} + [\text{PC} + (&lt;\text{expr} &gt; \times w + k)] )</td>
<td>( r[v] )\n( r[v] - \text{num}_t )\n( (r[v] - \text{num}_t) &lt;&lt; 24 ) &gt;&gt; 24</td>
</tr>
<tr>
<td>H</td>
<td>( \text{jcond } (r[v] &gt; \text{num}_a) \times \text{X} )\n( \text{jmp } [T + ((&lt;\text{expr} &gt; &amp; \text{mask}) \times 2^w) + w] )</td>
<td>( (r[v] - \text{num}_t) &gt;&gt; s) + )\n( (r[v] - \text{num}_t) )\n( (r[v] - \text{num}_t) &gt;&gt; 2^w) + )\n( (r[v] - \text{num}_t) &gt;&gt; 2^w + )\n( (r[v] - \text{num}_t) )</td>
</tr>
</tbody>
</table>

Examples of form O are given in the appendix.

5. Experimental results

We tested the technique for recovery of jump table branches on Pentium and SPARC binaries in a Solaris environment. The following integer SPEC95 benchmark programs were used for testing:

- go: artificial intelligence; plays the game of Go
- m88ksim: Motorola 88K chip simulator; runs test program
Fig. 8. Number of indexed jumps for SPARC benchmark programs.

<table>
<thead>
<tr>
<th>Benchmark</th>
<th>A</th>
<th>O</th>
<th>H</th>
<th>Unknown</th>
</tr>
</thead>
<tbody>
<tr>
<td>awk</td>
<td>0</td>
<td>2</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>vi (2.5)</td>
<td>10</td>
<td>1</td>
<td>9</td>
<td>0</td>
</tr>
<tr>
<td>vi</td>
<td>0</td>
<td>13</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>go</td>
<td>0</td>
<td>5</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>m88ksim</td>
<td>0</td>
<td>10</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>gcc</td>
<td>0</td>
<td>153</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>compress</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>li</td>
<td>0</td>
<td>3</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>ijpeg</td>
<td>0</td>
<td>3</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>perl</td>
<td>0</td>
<td>32</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>vortex</td>
<td>0</td>
<td>21</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>total</td>
<td>10</td>
<td>243</td>
<td>9</td>
<td>5</td>
</tr>
</tbody>
</table>

Fig. 8. Number of indexed jumps for SPARC benchmark programs.

1. gcc: GNU C compiler; builds SPARC code
2. compress: compresses and decompresses a file in memory
3. li: LISP interpreter
4. ijpeg: graphic compression and decompression
5. perl: manipulates strings (anagrams) and prime numbers in Perl
6. vortex: a database program
7. All benchmark programs were compiled with the Sun cc compiler version 4.2 on a Solaris 2.6 machine using standard SPEC optimizations (i.e. -O4 on SPARC and -O on Pentium). We also include results for the awk script interpreter utility, and the vi text editor (on both Solaris 2.5 and 2.6). These programs are part of the Unix OS.
8. Figs. 8 and 9 show the number of indexed jumps found in each benchmark program, the classification of such indexed jumps into the 3 normal forms (A, O and H), and any unknown types. In the case of SPARC code, most indexed jump tables are of form O, which means that the indexed table stores offsets from the start of the table to the destination target address. In the case of Pentium code, almost all indexed jump tables are of form A, meaning that the table contains the target addresses for each of the entries in the case statement. Unknown entries show the number of jump tables that were not recovered by this technique. These are normally due to highly optimized code that relies on indirect function calls, or on enumerated types which do not do any bounds checking.
9. The primary motivation for this work was to increase our coverage of decoded code in an executable program. We measured the coverage obtained from our technique using the size in bytes of the text segment(s) of the program, compared to the number
of bytes decoded and the number of bytes in jump tables. The figures do not necessarily add up to 100% due to unreachable code during the decoding phase. Also, in the case of SPARC, we duplicate some instructions in order to remove delayed branch instructions; this duplication is counted twice in our model, leading to slightly over 100% coverage in rare cases. Figs. 10 and 11 show the results of our coverage analysis. The results show that when indexed tables are present in the program, up to 90% more of the code can be reached by decoding such tables correctly.
Fig. 11. Coverage of code for Pentium benchmarks.

The *li* and *ijpeg* programs show a small coverage of their code sections. This is due to indirect calls on registers which are not yet analysed in our framework to determine their target addresses. In the case of *ijpeg*, a large percentage of the procedures are reached only via indirect calls, hence they are never decoded. In the context of our binary translation framework, we rely on an interpreter to process such code at runtime.

### 6. Previous work

Not much work has been published in the literature on recovery of indexed jump targets. These techniques tend to be ad hoc and tailored to a specific platform or compiler, and tend to rely on pattern matching.

The *qpt* binary profiler is a tool to profile and trace code on MIPS and SPARC platforms. Profiling and tracing is done by instrumenting the executable code. Jump tables are detected by relying on the way in which the compiler generated code for the jump, mainly by expecting the table to be in the data segment in the case of MIPS or in the code segment, immediately after the indirect jump, on the SPARC. The end of the table is found by examining the instructions prior to the indirect jump and determining the table’s size; alternatively, the text space is scanned until an invalid address is met [16].

The *dcc* decompiler is an experimental tool for decompiling 80286 DOS executables into C code. The method used in this tool was that of pattern matching against known patterns generated by several compilers on a DOS machine [5].

EEL is an executable editing library for RISC machines. Slicing is used to determine the instructions that affect the computation of the indirect jump and determine the jump table. No precise method is given. Measurements on the success of this technique on
Fig. 12. Form O example for SPARC assembly code.

```
10a58: 0x0009c ! Indexed table
10a5c: 0x000dc ! of offsets
10a60: 0x000fc
10a64: 0x0011c
...

sethi $hi(0x10800), $11 ! Set table address
add $11, 0x258, $11 ! into $11
...
ld $fp - 4, $10 ! Read idx variable
sub $10, 2, %o0 ! Subtract min val
cmp %o0, 5 ! Cmp with range-1
bgu 0x10b14 ! Exit if out of range
sll %o0, 2, %o0 ! Multiply by 4
ld (%o0 + $11), %o0 ! Fetch from table
jmp %o0 + $11 ! Jump to table+offset
nop ! Delay slot instr
```

SPARC using the SPEC92 benchmarks reveal that 100% recovery of indexed jumps is achieved for code compiled by the gcc and the Sun Fortran compilers, and 89% for the SunPro compilers. The recovery ratio was measured by counting the number of indirect jumps expected and recovered [17].

IDA Pro, a disassembler for numerous machines, makes use of undocumented techniques to determine which compiler was used to compile the original source program [15]. IDA Pro’s recovery of jump tables is good but their technique has not been documented in the literature.

Our techniques compare favourably with those of other tools. They have been tested extensively with code generated from different compilers on both CISC and RISC machines, indicating the generality and machine independence of the technique.

7. Conclusions

We have presented a technique based on slicing and copy propagation to understand and recover the code of n-conditional branches implemented by jump tables. The technique is suitable for recovery of code in machine-code manipulation tools such as binary translators, code instrumentors and decompilers.

Our technique has been tested on Pentium and SPARC code in a Solaris environment against the SPEC95 integer benchmark programs. Over 500 n-conditional branches were correctly detected in these programs, making this technique suitable for path coverage during the decoding of machine instructions. For the perl benchmark, over 90% of extra code was decoded due to this recovery technique.

This work is part of the retargetable binary translation project UQBT. For more information refer to http://www.csee.uq.edu.au/csm/uqbt.html
Fig. 13. Form O example for SPARC assembly code (vi 2.5) using position independent code. Offsets are relative to the address of the call instruction.

ldsb [%16], %0     ! Get switch var
clt %i3           ! (Not relevant)
sub %0, 2, %0     ! Subtract min value
cmp %0, 54        ! Cmp with range-1
giu 0x44acc       ! Exit if out of range
sll %0, 2, %0     ! Multiply by 4
43eb8:
call .+8          ! Set %0 = pc
seti [%hi(0x0)], %g1  ! Set %g1 = 0x0001c
or [%g1, 0x1c, %g1]  !
add %0, %g1, %0  ! %0 = 0x43eb8 + 0x1c
    ! = 0x43ed4
ld [%o7 + %0], %0 ! Fetch from table
jmp %o7 + %0     ! Jump to table+offset
nop               ! Delay slot instr
43ed4: 0x0021c     ! Table of offsets from
43ed8: 0x00af4     ! call instr to case code
43edc: 0x000f8     ! e.g. 0x43eb8 + 0x00f8
        ! = 0x43fb0
43ee0: 0x008d0
...

Fig. 14. A different form O example for SPARC assembly code, also using position independent code. This code is generated from the same source code as the example in Fig. 13, but with a different version of the compiler. Offsets are relative to the start of the table.

4233c:
call  .+8          ! Set %0 = pc
seti  [%hi(0xffffffff00)], %0  ! %0 = 0x02 = -1024
ldsb  [%i5], %0     ! %0 = <expr>
add  %0, 736, %0 ! %0 = %0 = -288
add  %0, %o7, %0 ! %0 = %0 = pc-288
sub  %0, 2, %0     ! Subtract min value
mov  %0, %07       ! (Not relevant)
mov  %0, %01       ! %0 = <expr>
cmp  %0, 54       ! Cmp with range-1
add  %i1, 1, %i1 ! (Not relevant)
bgui  0x42f58      ! Exit if out of range
sll  %0, 2, %0     ! Multiply <expr> by 4
ld [%o0 + %01], %0 ! Fetch from table
jmp  %o0 + %01    ! Jump to table+offset
nop         ! Delay slot instr

(288 bytes earlier than the call instruction):
4221c: 0x298     ! Table of offsets from
42220: 0x73c     ! table to case code
42228: 0x15c     ! e.g. 0x4221c + 0x15c
        ! = 0x42378
4222c: 0x8fc
...
Appendix

Figs. 12 and 13 illustrate two examples of form O from SPARC code. The former contains an indexed table of offsets from the table to the code that handles each individual switch case. The latter also contains an indexed table of offsets from the table to the code, however, the way the address of the table is calculated is position independent code (via the call to `.+8`, which produces the side-effect of setting the `o7` register with the current program counter).

A different form O example for SPARC assembly code is shown in Fig. 14.

References